

X10 Micro OCS Datasheet

Model A Built-In I/O: 12 Digital In, 12 Digital Out, 4 Analog In/RTD IN, 2 Analog Out Model R Built-In I/O: 12 Digital In, 6 Relay Out, 2 PWM Out, 4 Analog In/RTD In, 2 Analog Out

MAN1278-20_X10_DS _____ Table of Contents



Part Numbers

Model R: Relay & Solid State Outputs	HE-X10R
Model A: Solid State Outputs	HE-X10A

User Manual and Add-Ons

Find the documents via the Documentation Search.

Part #	Description
MAN1277	HE-X10 User Manual
HE-BAT009	3V Lithium Coin Battery
HE-XCK	Programming Cables
HE-FBD001	Ferrite core for filtering out electrical
	noise.
HE200MJ2TRM	Adapter, RJ45 (8P8C) male to 8-pos-
	ition terminal strip.

Battery Maintenance

The X10 has an advanced battery system that uses a lithium coin battery. The battery powers the real time clock when power is removed, and it is needed for register data retention. Manual **MAN1277** via the <u>Documentation Search</u> for more details on battery replacement.

Part Numbers User Manual and Add-Ons Battery Maintenance	1
TECHNICAL SPECIFICATIONS	2
General Specifications	2
Connectivity	2
Control and Logic	2
User Interface	
Testing	2
CONTRŎLLER OVERVIEW	3
Overview of OCS	3
Power Wiring	3
DIGITAL & RELAY I/O SPECIFICATIONS	
Digital DC Inputs: Models R & A	4
Model A: Digital DC Outputs, Sourcing	4
Model R: Digital DC Outputs, Sinking, Sourcing	
Relay Outputs: Model R	4
ANALOG I/O SPECIFICATIONS	
Analog Inputs, Models R & A	
Analog Outputs, Models R & A	
WIRING: INPUTS AND OUTPUTS	
Analog Inputs Information	
Digital Inputs	
Relay Life	
Inserting and Removing Connectors	
Built-In I/O: Models R & A	
J1 & J2 WIRING J3 WIRING - Models A & R	
COMMUNICATIONS	
Serial Communication	
Ethernet	
CAN Communications	
Discreet Wiring	
DIMENSIONS & INSTALLATION	12
X10 Dimensions	
Installation Procedure	
SAFETY & MAINTENANCE	
Warnings	
FCC Compliance	
Technical Support	
Precautions	13



TECHNICAL SPECIFICATIONS

General Specifications

Primary Pwr. Range	9 - 30VDC	
	X10A	X10R
Typical power back- light 100%	305mA @ 24V	295mA @ 24V
Typical Power back- light 50%	205mA @ 24V	200mA @ 24V
Power Backlight Off	140mA @ 24V	140mA @ 24V
Inrush Current	30A < 1ms	
Real Time Clock	Battery backed; lithium coin cell CR2450	
Battery Life	7 -10 years	
Clock Accuracy	+/- 90 secs/month @ 20°C	
Relative Humidity	5 to 95% Non-condensing	
Operating Temp.	-10°C to +60°C	
Storage Temp.	-20°C to +70°C	
Temperature Code	T4	
Pollution Degree	2	
Altitude Limit	Up to 2000m	
Weight	39 oz. / 1105.6g	
Mounting Clips	4, metal	
Housing Material	Polycarbonate, UL rated	
Environmental Ratings	1, 4X (indoor use only), 12, 12K & 13	

Connectivity

Serial Ports	1 x RS232, 1 x RS485	
485 Terminations	On-board, software controlled	
Mini USB	Programming Only	
CAN Hardware	CAN 2.0	
CAN Port Connector	RJ45 (Red)	
CAN Port Speeds Support	125kB, 250kB, 500kB, 1Mb/sec.	
CAN Protocols	CsCAN	
Ethernet	1 x 10Mbps/100Mbps	
Removable Memory In	microSD (SDHC, SDXC IN FAT32 format, support for 32GB max. Application Updates, Datalogging, more)	

Control and Logic

Control Language Support	Advanced ladder logic Full IEC 61131-3 languages
Logic Program Size	256kB
Non-Retentive Memory	128kB
Internal Storage Memory	16Mb
Total Program Memory	2.5Mb
Logic Scan Rate	0.4ms/kB
%I (Digital Inputs)	1024
%Q (Digital Outputs)	1024
%AI (Analog Inputs)	256
%AQ (Analog Outputs)	256
%M (Retentive Bits)	1024
%T (Temporary Bits)	1024
%R (Retentive Registers)	5000
%D (Display Bits)	250
%K (Key Bit)	4
%S (Status Bits)	13

User Interface

Display Type	7" 65k Color; 300 cd/m ² (nits)	
Resolution	800 X 480 pixels	
Backlight	White LED	
Reaklight Lifetime	20,000 hrs to reach	
Backlight Lifetime	50% brightness	
Backlight Control	Software controlled (ON/OFF)	
User-Programmable	250	
Screens/Pages		
No. of Objects /	100	
Screens		
Screen Memory	256kB	
Keypad	Touch screen	
Tactile Feedback	Optional Sound	
	Max 30 per page + touch system	
Number of Keys	and four function keys	

Testing

Shock	IEC 60068-2-27	
Vibration	IEC 60068-2-6	
UL Environmental Rat-	Type 1, 4, 4X, 12, 12k & 13 (for	
ings	indoor use only)	
Certifications (UL/CE)	North America Europe	



CONTROLLER OVERVIEW

Overview of OCS



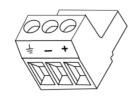


- 1. Touchscreen
- 2. High-capacity microSD Slot
- 3. RS232/RS485 Serial Connector, CAN port (via RJ45),
- LAN Port (Ethernet)
- 4. USB Mini-B Port
- 5. Analog I/O, DC Inputs, DC Outputs
- 6. DC Power

NOTE: See "Precautions" on page 13 about USB and grounding.

Power Wiring

NOTE: The Primary Power Range is 10VDC to 30VDC.



Primary Power Port Pins		
PIN Signal Description		Description
1	Ground	Frame Ground
2	DC-	Input Power Supply Ground
3	DC+	Input Power Supply Voltage

DC Input / Frame

- Solid/Stranded Wire: 12-24 awg (2.5-0.2mm)
- Strip length: 0.28" (7mm)
- Torque, Terminal Hold-Down Screws: 4.5 7 in-lbs (0.50 – 0.78 N-m)
- DC- is internally connected to I/O V-, but is isolated from CAN V-. A Class 2 power supply must be used.

Power Up

1. **Optional**: Attach ferrite core with a minimum of two turns of the DC+ and DC- signals from the DC supply that is powering the controllers. See page 1.



- 2. Connect to earth ground.
- 3. Apply recommended power.



DIGITAL & RELAY I/O SPECIFICATIONS

Digital DC Inputs: Models R & A

Inputs per Module	12 including 4 configurable HSC inputs	
Commons per Module		1
Input Voltage Range	12VDC	/ 24VDC
Absolute Max. Voltage	30VDC Max.	
Input Impedance	10kΩ	
Input Current	Positive Logic	Negative Logic
Upper Threshold	0.8mA	-1.6mA
Lower Threshold	0.3mA	-2.1mA
Max. Upper Threshold	8VDC	
Min. Lower Threshold	3VDC	
OFF to ON Response	0.1ms	
ON to OFF Response	0.1ms	
Number of Counters	4	
Maximum Frequency	500kHz	
Accumulator Size	32-bits each	
	Totalizer, quadrature, pulse	
Modes Supported	measurement, frequency	
would bupperted	measurement, set-point	
	controlled outputs	

Model R: Digital DC Outputs, Sinking, Sourcing

Outputs per Module	2 (PWM or HSC)		
· · ·	2 (PWM or HSC)		
Commons per Module	1		
Туре		Sinking	
Absolute Max. Voltage		28VDC	
Output Protection	Sh	ort Circuit	
Max. Output per Point: Sinking	0.5A		
Max. Output per Point: Sourcing	2.4mA @ 24V		
Max. Voltage Drop at Rated Current	0.25VDC		
Max Outrush	650mA		
	Min Max		
OFF to ON Time (typ- ical)	2.2µs	2.2µs + Scan Time	
ON to OFF Time (typ- ical)	13µs	13µs + Scan Tiime	
PWM Out	65kHz		
Rise Time	2.4µs (typical @ 24V)		
Fall Time	7.5µs (typical @ 24V)		

Model A: Digital DC Outputs, Sourcing

Outputs per Module	12 Including 2 Configurable PWM Outputs	
Commons per Module		2
Туре	Sourcing	
Absolute Max. Voltage	28VDC	
Output Protection	Short Circuit, Thermal, Undervoltage	
Max. Voltage Drop at Rated Current	0.25VDC	
Max Output per Point: Sourcing	0.5A @ 24VDC	
	Min	Max
OFF to ON Time (typ- ical)	300ns	500ns + Scan Time
ON to OFF Time (typ- ical)	300ns	475 = Scan Time
PWM Out	65kHz	
Rise Time	150ns Max	
Fall Time	150ns Max	

Relay Outputs: Model R

Outputs per Module	6 Relay	
Relay Contact Type	Floating	
Max. Output Current &	3A @ 60VAC, resistive	
Voltage per Relay	3A @ 30VDC, resistive	
Max. Total Output Cur-	5A continuous	
rent	5A continuous	
Max. Switched Power	150W	
Contact Isolation to	1000VAC	
Ground	TUUUVAC	
Max. Voltage Drop at	0.5V	
Rated Current	0.50	
Expected Life (see	No Load : 5,000,000	
derating chart)	Rated Load: 100,000	
Max Switching Pata	300 CPM at no load 20 CPM at	
Max. Switching Rate	rated load	
Туре	Mechanical Contact	
	One update per	
Response Time	ladder scan plus 10 ms	



ANALOG I/O SPECIFICATIONS

Analog Inputs, Models R & A

Numero an of Observation	4	
Number of Channels	4	
Input Ranges	0-20mA; 4-20mA; RTD100	
RTD Temperature	-50° to 200°C (-58° to 392°F)	
Range	PT100 DIN	
Nominal Resolution	12 Bits	
Resolution	0.5°C	
Safe Input Voltage	-0.5V to 12V,	
Range	protection up to 24V	
Input Impedance (clamped @ -0.5VDC to 12VDC)	Current Mode: 100Ω	
%AI Full Scale	20mA: 32,000 full scale RTD: 20 Counts/°C	
Max. Over Current	25mA	
Max Error at 25°C (excluding Zero)	< 1.5% of full scale	
Filtering	160 Hz Hash (noise) Filter, 1-128 Scan Digital Running Average Filter	

Analog Outputs, Models R & A

Number of Channels	2		
Output Ranges	4-20mA		
Nominal Resolution	12 Bits		
Update Rate	Once per PLC scan		
Max. Error at 25°C	< 1.5% of full scale		
(Excluding Zero)			
Maximum 20mA Load	500Ω		
% AQ Full Scale	32,000		
Protection	Protect against miswire up to 24VDC auto-recover		



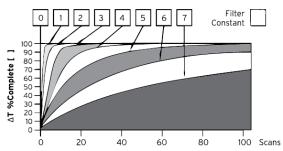
WIRING: INPUTS AND OUTPUTS

Relay Life

Analog Inputs Information

Raw input values for channels 1-4 are found in the registers as Integer- type data with a range from 0 - 32000.

Analog inputs may be filtered digitally with the Filter Constant found in the Cscape Hardware Configuration for Analog Inputs. Valid filter values are 0-7 and act according to the following chart:



Data Values		
Input Mode:	Data Format, 12-bit INT:	
0-20mA, 4-20mA	0-32000	
RTD	20 Counts/ °C	

Relay Life Expectancy

WARNING: Exposure to some chemicals may degrade the sealing proper- ties of materials used in the Tyco relay PCJ. **Cover/Case & Base**: Mistubishi engineering Plastics Corp. 5010GN6-30 or 5010GN6-30 M8 (PBT)

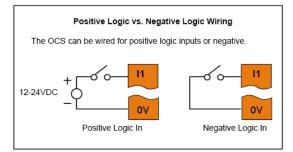
Sealing Material: Kishimoto 4616-50K (I part epoxy resin)

Inserting and Removing Connectors

To Insert: Using a small screwdriver, firmly press on connector on one end and then the other until connector clicks into place. Ensure connector is firmly seated.

To Remove: Use a small screwdriver on each side of connector to gently pry up the connector.

Digital Inputs



Digital inputs may be wired in either a Positive Logic or Negative Logic fashion as shown. The setting in the Cscape Hardware Configuration for the Digital Inputs must match the wiring used in order for the correct input states to be registered.

Built-In I/O: Models R & A

Fixed Address	I/O Function	Model R	Model A
	Digital Inputs	1-12	1-12
%I	Reserved	13-32	13-32
	Digital Outputs	1-2	1-12
	Relay Outputs	3-8	
%Q	Reserved	9-24	13-24
	Analog Inputs	1-4	1-4
%AI	Reserved	5-12	5-12
	Analog Outputs	1-2	1-2
%AQ	Reserved	3-16	3-16



J1 & J2 WIRING

J1 Wiring: Model A - Digital Out

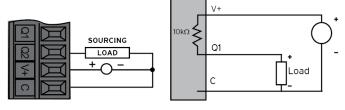
POSITION/PIN		DIGITAL MODEL
1	Q1 (%Q1)	Dig. Out 1 (PWM)
2	Q2 (%Q2)	Dig. Out 2 (PWM)
3	Q3 (%Q3)	Dig. Out. 3
4	Q4 (%Q4)	Dig Out. 4
5	V+	External V+
6	С	Common
7	Q5 (%Q5)	Dig Out. 5
8	Q6 (%Q6)	Dig Out. 6
9	Q7 (%Q7)	Dig Out. 7
10	Q8 (%Q8)	Dig Out. 8
11	Q9 (%Q9)	Dig Out. 9
12	Q10 (%Q10)	Dig Out. 10
13	Q11 (%Q11)	Dig Out.11
14	Q12 (%Q12)	Dig Out. 12
15	V+	External V 2 +
16	С	Common

Q1	Ŋ	LOAD
Q2	A	
ຊ		LOAD
8		LOAD
+		+
т О		Ŭ
g		
5 Q6		
6 Q7		
80		
8		
QD	E	
Q1	回	
Q12	E	LOAD
4	E	+ 0 -
ဂ	E	

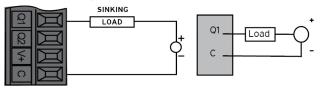
NOTE: Internal 10k Ω resistors between: V+ and Q1; V+ and Q2

Sinking & Sourcing Wiring on Model R

Model R: Sourcing Outputs [2.4mA @ 24V]

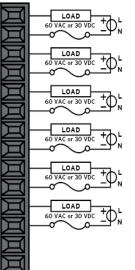


Model R: Sinking Outputs [Outputs can sink 500mA]



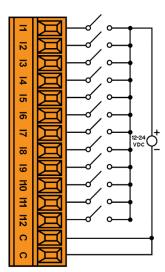
J1 Wiring: Model R - Relay / Digital Out

POSITION/PIN DIGITAL MODEL 1 R1 (%Q3) Relay 1 N.O. 2 C1 (%Q3) Relay 1 C		
2 C1 (%Q3) Relay 1 C	POSITION/PIN	
	1	
	2	
3 R2 (%Q4) Relay 2 N.O.	3	
4 C2 (%Q4) Relay 2 C	4	
5 R3 (%Q5) Relay 3 N.O.	5	
6 C3 (%Q5) Relay 3 C	6	
7 R4 (%Q6) Relay 4 N.O.	7	
8 C4 (%Q6) Relay 4 C	8	
9 R5 (%Q7) Relay 5 N.O.	9	
10 C5 (%Q7) Relay 5 C	10	
11 R6 (%Q8) Relay 6 N.O.	11	
12 C6 (%Q8) Relay 6 C	12	
13 Q1 (%Q1) Dig. OUT 1	13	
14 Q2 (%Q2) Dig. OUT 2	14	
15 V+ External V+	15	
16 C Common	16	



J2 Wiring: Models R & A - Digital Input

POSITION/PIN		DIGITAL MODEL
1	1 (% 1)	Dig. IN 1
2	12 (%12)	Dig. IN 2
3	13 (%13)	Dig. IN 3
4	4 (% 4)	Dig. IN 4
5	15 (%15)	Dig. IN 5
6	16 (%16)	Dig. IN 6
7	17 (%17)	Dig. IN 7
8	18 (%18)	Dig. IN 8
9	19 (%19)	Dig. IN 9 (HSC)
10	110 (%110)	Dig. IN 10 (HSC)
11	11 (% 11)	Dig. IN 11 (HSC)
12	l12 (%l12)	Dig. IN 12 (HSC)
13	С	Common
14	С	Common

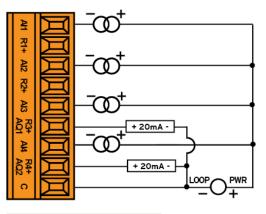




J3 WIRING - Models A & R

4 X 4-20mA Input / 4-20mA Output

PIN	Wire			
1	Al1 (%Al1)			
2	R1+ (%Al1)			
3	AI2 (%AI2)			
4	R2+ (%AI1)			
5	AI3 (AI3/%AQ1)			
6	R3+ or AQ1 (AI3/%AQ1)			
7	AI4 (AI4/%AQ2)			
8	R4+ or AQ2 (AI4/%AQ2)			
9	С			



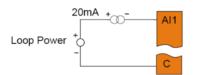
If AQ1 is used, RTD3 is unavailable. If AQ2 is used, RTD4 is unavailable.

RTD: 2 x 3 - Wire RTD & 2 x 4-20mA Output

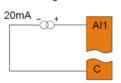
PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%AI1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%AI2)	RTD Excitation
5	AI3 (AI3/%AQ1)	No Connection
6	R3+ or AQ1 (AI3/%AQ1)	mA Output
7	AI4 (AI4/%AQ2)	No Connection
8	R4+ or AQ2 (AI4/%AQ2)	mA Output
9	С	Common

Universal Wiring Schematic

20mA Analog In - Not Self Powered

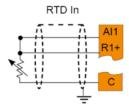


20mA Analog In - Self Powered



4 - 20mA Analog Out

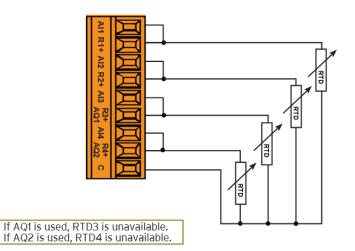






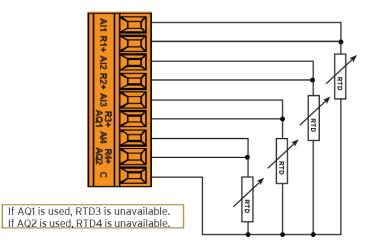
RTD: 4 x 2 - Wire RTD Connection

PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%Al1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%Al1)	RTD Excitation
5	AI3 (AI3/%AQ1)	RTD Sense
6	R3+ or AQ1 (AI3/%AQ1)	RTD Excitation
7	AI4 (AI4/%AQ2)	RTD Sense
8	R4+ or AQ2 (AI4/%AQ2)	RTD Excitation
9	С	Common

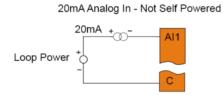


RTD: 4 x 3 - Wiring RTD Connection

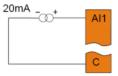
PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%Al1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%Al1)	RTD Excitation
5	AI3 (AI3/%AQ1)	RTD Sense
6	R3+ or AQ1 (Al3/%AQ1)	RTD Excitation
7	AI4 (AI4/%AQ2)	RTD Sense
8	R4+ or AQ2 (AI4/%AQ2)	RTD Excitation
9	С	Common



Universal Wiring Schematic

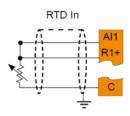


20mA Analog In - Self Powered



4 - 20mA Analog Out







COMMUNICATIONS

Serial Communication

MJ1/2 Serial Ports



2 Serial Ports on 1 Module Jack (8posn)

MJ1: RS-232 w/Full Handshaking

MJ2: RS-485 Half-Duplex - RS-485 termination and biasing via System Menu or System Register

	MJ1 & MJ2 PINS		
PIN	SIGNAL	DIRECTION	
8	TXD	OUT	
7	RXD	IN	
6	0V	COMMON	
5	+5V @ 60mA	OUT	
4	RTS	OUT	
3	CTS	IN	
2	RX-/TX-	IN / OUT	
1	RX+/TX+	IN / OUT	

NOTE: Attach optional Ferrite Core (HE-FBD001) with a minimum of two turns of serial cable.

Ethernet



Green LED indicates link - when illuminated, data communication is available. **Yellow LED indicates activity** - when flashing, data is in transmission.



CAN Communications



Modular jack (8 posn RJ45)

	MJ1 & MJ2 PINS		
PIN	SIGNAL	DIRECTION	
8	TXD	OUT	
7	RXD	IN	
6	0V	COMMON	
5	+5V @ 60mA	OUT	
4	RTS	OUT	
3	CTS	IN	
2	RX-/TX-	IN / OUT	
1	RX+/TX+	IN/OUT	

The CAN port is provided via the single 8-position modular jack labeled "CAN". It may be used to communicate with other OCS products using Horner's CsCAN protocol. Additionally, remote expansion I/O such as SmartRail, SmartB-lock, and SmartStix may be implemented using the CsCAN protocol.

Termination for the CAN port may be enabled from the System Menu or System Register. This should only occur if the X4 is at either end of the CAN network. Only the two devices on either end of the CAN network should be terminated.

Discreet Wiring

For CAN or serial connections the <u>HE200MJ2TRM</u> accessory will provide a modular connector to wiring block adapter for installations that require descreet wiring.





DIMENSIONS & INSTALLATION

X10 Dimensions



Panel Tolerance +/- 1.0mm

Installation Procedure

- This equipment is panel mounted and is meant to be installed in an enclosure suitable for the environment, such that the back of the equipment is only accessible with the use of a tool.
- Requires a Class 2 Power Source.
- This equipment is suitable for use in Class I, Division 2, Groups A, B, C and D; Class II, Division 2 Groups F and G; and Class III Hazardous Locations or Non-Hazardous Locations only.
- The X10 utilizes a clip installation method to ensure a robust and watertight seal to the enclosure. Follow the steps below for the proper installation and operation of the unit.

Please following the steps below for the proper installation and operation of the unit.

- Carefully locate an appropriate place to mount the X10. Be sure to leave enough room at the top of the unit for insertion and removal of the microSD[™] card.
- Carefully cut the host panel per the diagram, creating a 175mm x 131.9mm (with a tolerance of +/-1.0mm) opening into which the X10 is to be installed. If the opening is too large, water may leak into the enclosure, potentially damaging the unit. If the opening is too small, the OCS may not fit through the hole without damage.
- 3. Remove any burrs/sharp edges and ensure the panel is not warped in the cutting process.
- Install and tighten the four mounting clips (provided in the box) until the gasket forms a tight seal. For standard composite mounting clips (included with product). NOTE: Torque rating is 2-3 in-lbs (0.23-0.34 Nm). For optional metal mounting clips, use a torque rating of 4-8 in-lbs (0.45-0.90 Nm).
- 5. Connect communications cables to the serial port, USB ports, and CAN port as required.



SAFETY & MAINTENANCE

Warnings

- To avoid the risk of electric shock or burns, always connect the safety (or earth) ground before making any other connections.
- 2. To reduce the risk of fire, electrical shock, or physical injury, it is strongly recommended to fuse the voltage measurement inputs. Be sure to locate fuses as close to the source as possible.
- 3. Replace fuse with the same type and rating to provide protection against risk of fire and shock hazards.
- 4. In the event of repeated failure, do NOT replace the fuse again as repeated failure indicates a defective condition that will NOT clear by replacing the fuse.
- 5. Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment.
- 6. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.
- 7. **WARNING** Battery may explode if mistreated. Do not recharge, disassemble, or dispose of in fire.
- 8. WARNING EXPLOSION HAZARD Batteries must only be changed in an area known to be non-hazardous.
- 9. **WARNING** Do not disconnect while circuit is live unless are is know to be non-hazardous.

FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following

two conditions:

- 1. This device may not cause harmful interference.
- 2. This device must accept any interference received, including interference that may cause undesired operation.

Technical Support

North America

1 (317) 916-4274 (877) 665-5666 www.hornerautomation.com techsppt@heapg.com

Europe

+353 (21) 4321-266 www.hornerautomation.eu technical.support@horner-apg.com

Precautions

All applicable codes and standards need to be followed in the installation of this product. Adhere to the following safety precautions whenever any type of connection is made to the module:

- 1. Connect the safety (earth) ground on the power connector first before making any
- 2. other connections.
- 3. When connecting to the electric circuits or pulse-initiating equipment, open their
- 4. related breakers.
- 5. Do NOT make connection to live power lines.
- 6. Make connections to the module first; then connect to the circuit to be monitored.
- 7. Route power wires in a safe manner in accordance with good practice and local codes.
- 8. Wear proper personal protective equipment including safety glasses and insulated gloves when making connections to power circuits.
- 9. Ensure hands, shoes, and floor are dry before making any connection to a power line.
- 10. Make sure the unit is turned OFF before making connection to terminals.
- 11. Make sure all circuits are de-energized before making connections.
- 12. Before each use, inspect all cables for breaks or cracks in the insulation. Replace
- 13. immediately if defective.
- 14. Use copper conductors in Field Wiring only, 60/75°C.
- 15. Use caution when connecting controllers to PCs via serial or USB. PCs, especially laptops,may use "floating power supplies" that are ungrounded. This could cause a damaging voltage potential between the laptop and controller. Ensure the controller and laptop are grounded for maximum protection. Consider using a USB isolator due to voltage potential differences as a preventative measure.